

Mining (maximal) span-cores from temporal networks

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Agenda

- 1 Temporal networks
- 2 Background and related work
- 3 Span-core decomposition
- 4 Maximal span-cores
- 5 Experiments
- 6 Applications
- 7 Conclusions

Temporal networks

Temporal networks

- a temporal network is a representation of
 - ▶ **entities** (vertices)
 - ▶ their **relations** (links)
 - ▶ how these relations are **established/broken along time**

Temporal networks

- a temporal network is a representation of
 - ▶ **entities** (vertices)
 - ▶ their **relations** (links)
 - ▶ how these relations are **established/broken along time**
- extracting **dense structures** together with their **temporal span** is a key mining primitive
 - ▶ quantify the transmission opportunities of respiratory infections
 - ▶ identify events and buzzing stories
 - ▶ understand the dynamics of collaboration in successful professional teams

Temporal graphs

Definition

A **temporal graph** is a triplet $G = (V, T, \tau)$, where

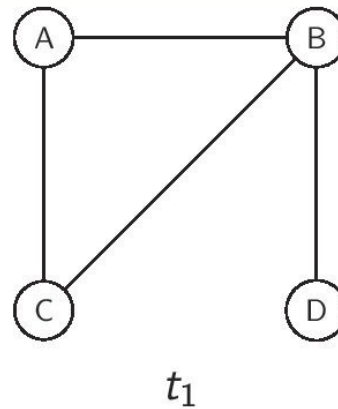
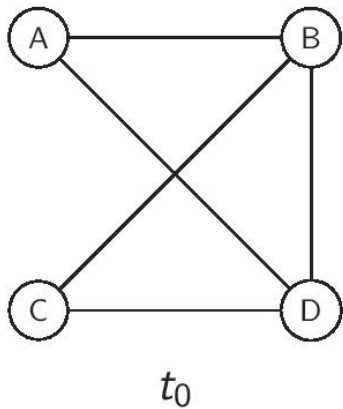
- V is a set of vertices,
- $T = [t_0, t_1, \dots, t_{max}] \subseteq \mathbb{N}$ is a discrete time domain,
- $\tau : V \times V \times T \rightarrow \{0, 1\}$ is a function defining for each $u, v \in V$ and each $t \in T$ whether edge (u, v) exists in t .

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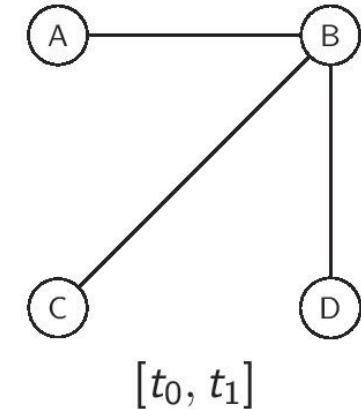
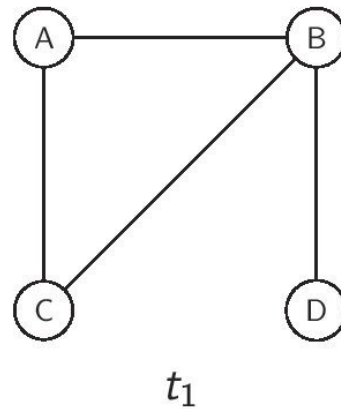
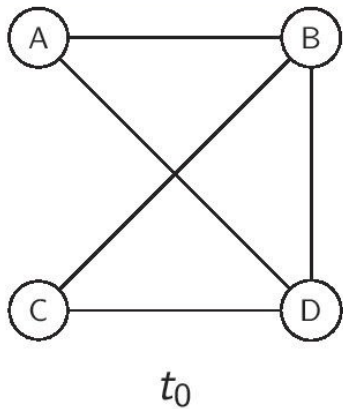


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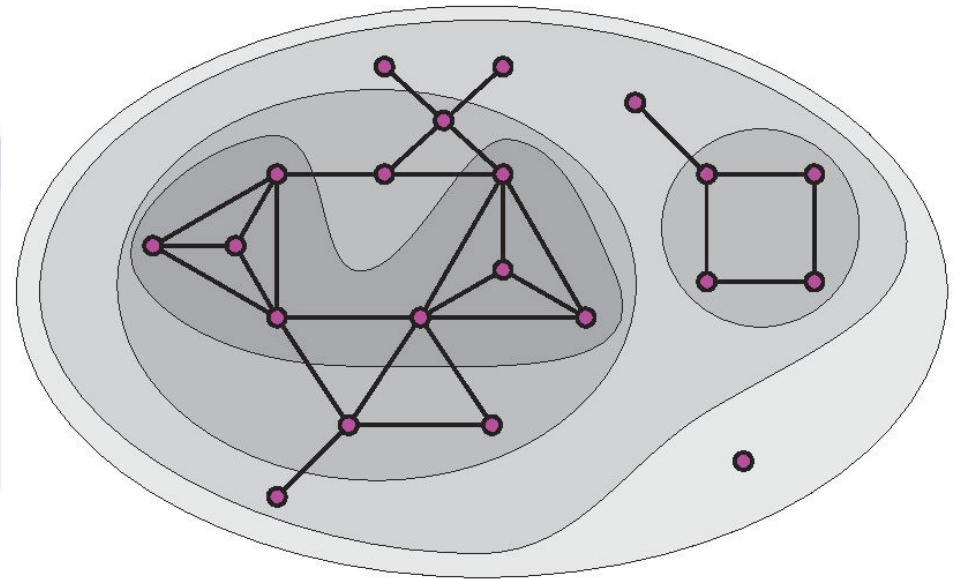
Background and related work

Core decomposition

Definition

The **k-core** (or core of order k) of a simple graph $G = (V, E)$ is a maximal set of vertices $C_k \subseteq V$ such that $\forall u \in C_k : \deg(C_k, u) \geq k$.

The set of all k -cores $V = C_0 \supseteq C_1 \supseteq \dots \supseteq C_{k^*}$ is the **core decomposition** of G .



Core decomposition in multilayer networks [Galimberti *et al.* 2017]

Definition

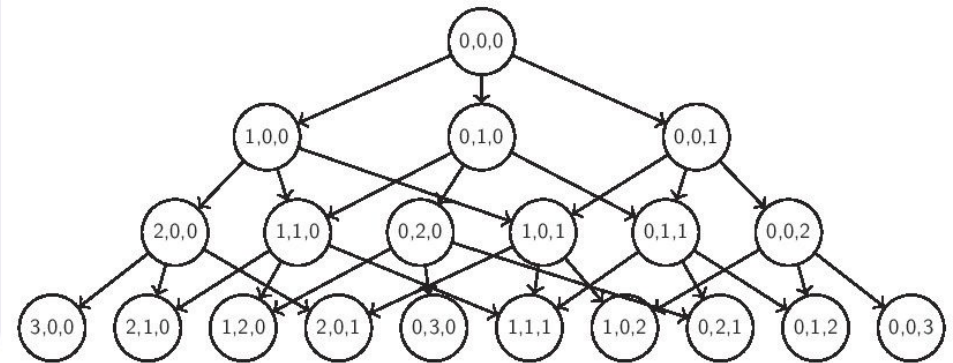
Given a multilayer graph $G = (V, E, L)$ and an $|L|$ -dimensional integer vector $\vec{k} = [k_\ell]_{\ell \in L}$, the **multilayer \vec{k} -core** of G is a maximal set of vertices $C_{\vec{k}} \subseteq V$ such that $\forall u \in C_{\vec{k}}, \forall \ell \in L : \text{deg}(C_{\vec{k}}, \ell, u) \geq k_\ell$.
The set of all \vec{k} -cores is the **multilayer core decomposition** of G .

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- the number of multilayer cores is **exponential** in the number of layer
- layers are not ordered, **there is not sequentiality**



Core decomposition in complex networks

- *Core Decomposition of Uncertain Graphs* [Bonchi *et al.* 2014]
 - ▶ defined the (k, η) -core as the largest subgraph in which **the probability that every vertex has degree no less than k is greater or equal to η**
- *Core decomposition in large temporal graphs* [Wu *et al.* 2015]
 - ▶ defined the (k, h) -core as the largest subgraph in which every vertex has at least **k neighbors** and at least **h temporal connections** with each of them
 - ▶ **the sequentiality of connections is not taken into account**: non-contiguous timestamps can support the same core
- *When engagement meets similarity: efficient (k, r) -core computation on social networks* [Zhang *et al.* 2017]
 - ▶ studied the problem of **enumerating all maximal cores** of a (non-temporal) variant of core decomposition
 - ▶ **the problem is NP-hard**

Span-core decomposition

Span-core decomposition

Definition

The **(k, Δ) -core** of a temporal graph $G = (V, T, \tau)$ is a maximal and non-empty set of vertices $\emptyset \neq C_{k, \Delta} \subseteq V$, such that $\forall u \in C_{k, \Delta} : \deg_{\Delta}(C_{k, \Delta}, u) \geq k$, where $\Delta \sqsubseteq T$ is a temporal interval and $k \in \mathbb{N}^+$.

- $\deg_{\Delta}(C_{k, \Delta}, u)$ represents the **degree of a vertex u in the subgraph induced by $C_{k, \Delta}$ within the temporal interval Δ**

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Problem

Given a temporal graph G , find the set of all (k, Δ) -cores of G .

- the number of span-cores is $\mathcal{O}(|T|^2)$

A naïve approach

Algorithm

- generate all temporal intervals $\Delta \sqsubseteq T$
- for each $\Delta \sqsubseteq T$, compute the subgraph $G_\Delta = (V, E_\Delta)$
- run a core-decomposition subroutine on each G_Δ

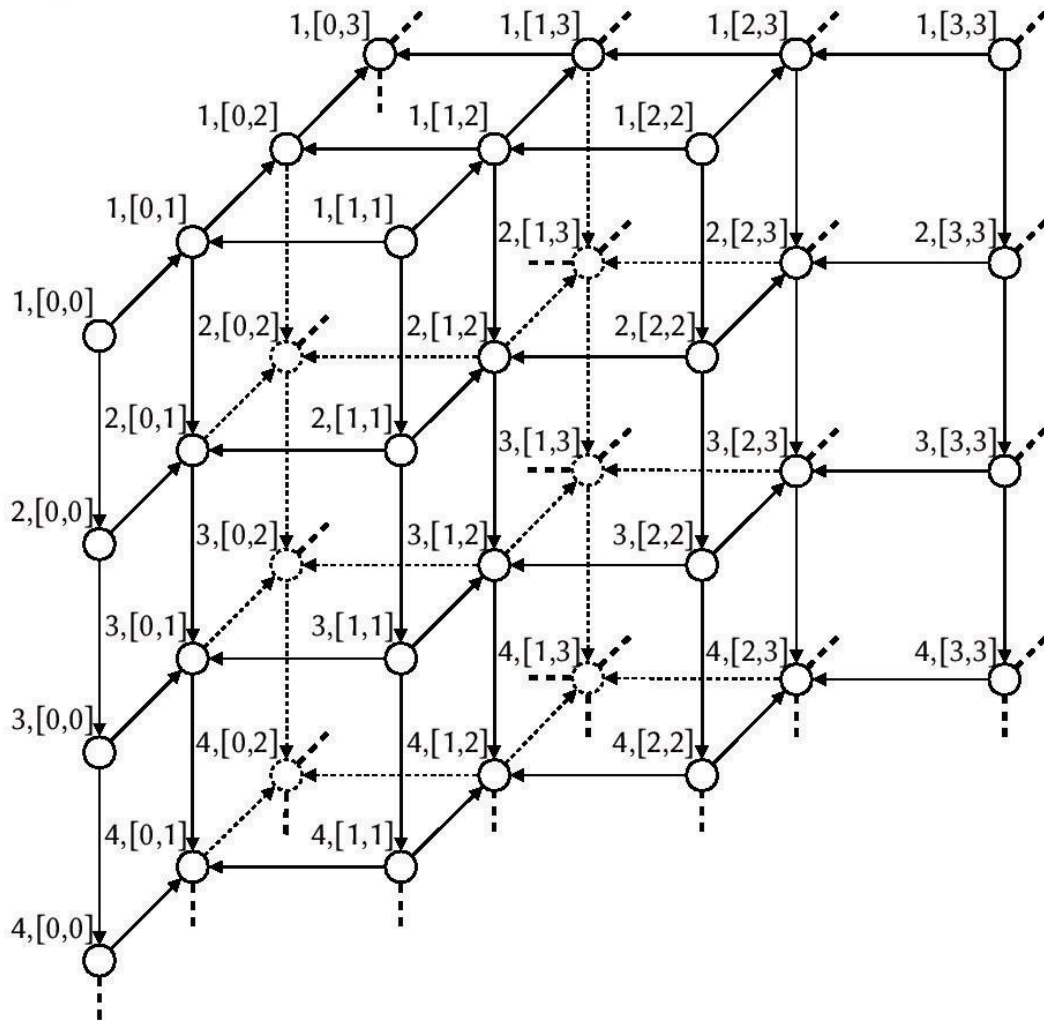
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- the time complexity is $\mathcal{O}(|T|^2 \times |E|)$

Span-core search space



Proposition

For any two span-cores $C_{k,\Delta}$, $C_{k',\Delta'}$ of a temporal graph G it holds that

$$k' \leq k \wedge \Delta' \sqsubseteq \Delta \Rightarrow C_{k,\Delta} \subseteq C_{k',\Delta'}$$

Corollary

Given a temporal graph $G = (V, T, \tau)$, and a temporal interval $\Delta = [t_s, t_e] \sqsubseteq T$, let $\Delta_+ = [\min\{t_s + 1, t_e\}, t_e]$ and $\Delta_- = [t_s, \max\{t_e - 1, t_s\}]$. It holds that

$$C_{k,\Delta} \subseteq (C_{k,\Delta_+} \cap C_{k,\Delta_-}) = \bigcap_{\Delta' \sqsubseteq \Delta} C_{k,\Delta'}$$

A more efficient algorithm

Algorithm

- generate temporal intervals $\Delta \sqsubseteq T$ of **increasing** size
- for each $\Delta \sqsubseteq T$ such that $|\Delta| > 1$, run a core-decomposition subroutine from $(C_{1,\Delta_+} \cap C_{1,\Delta_-})$
- if C_{1,Δ_+} or C_{1,Δ_-} does not exist, skip the core decomposition for Δ

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Maximal span-cores

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A span-core $C_{k,\Delta}$ of a temporal graph G is said **maximal** if there does not exist any other span-core $C_{k',\Delta'}$ of G such that $k \leq k'$ and $\Delta \sqsubseteq \Delta'$.

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Problem

Given a temporal graph G , find the set of all maximal (k, Δ) -cores of G .

- the number of maximal span-cores is $\mathcal{O}(|T|^2)$
- experimentally, maximal span-cores are **at least one order of magnitude less** than the overall span-cores

A filtering approach

Algorithm

- equip the algorithm for span-core decomposition with a data structure \mathcal{M} that
 - ▶ stores the span-core of the highest order for every temporal interval $\Delta \subseteq T$
 - ▶ at the storage of a span-core $C_{k,\Delta}$, removes the span-cores dominated by $C_{k,\Delta}$
- return the span-cores retained by \mathcal{M}

Properties of maximal span-cores

Lemma

Given a temporal graph $G = (V, T, \tau)$, let \mathbf{C}_M be the set of all maximal span-cores of G , and $\mathbf{C}_{\text{inner}} = \{C_{k^*}[G_\Delta] \mid \Delta \sqsubseteq T\}$ be the set of innermost cores of all graphs G_Δ . It holds that $\mathbf{C}_M \subseteq \mathbf{C}_{\text{inner}}$.

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Lemma

Given a temporal graph $G = (V, T, \tau)$, and three temporal intervals $\Delta = [t_s, t_e] \sqsubseteq T$, $\Delta' = [t_s - 1, t_e] \sqsubseteq T$, and $\Delta'' = [t_s, t_e + 1] \sqsubseteq T$. The innermost core $C_{k^*}[G_\Delta]$ is a maximal span-core of G if and only if $k^* > \max\{k', k''\}$ where k' and k'' are the orders of the innermost cores of $G_{\Delta'}$ and $G_{\Delta''}$, respectively.

Lemma

Given G , Δ , Δ' , Δ'' , k' , and k'' as in previous Lemma, let $\tilde{V} = \{u \in V \mid \deg_\Delta(V, u) > \max\{k', k''\}\}$, and let $C_{k^*}[G_\Delta[\tilde{V}]]$ be the innermost core of $G_\Delta[\tilde{V}]$. If $k^* > \max\{k', k''\}$, then $C_{k^*}[G_\Delta[\tilde{V}]]$ is a maximal span-core; otherwise, no maximal span-core exists for Δ .

Efficient maximal-span-core finding

Algorithm

- consider intervals $\Delta = [t_s, t_e] \sqsubseteq T$, for increasing values of t_s and decreasing values of t_e
 - ▶ e.g., with $t_{max} = 10$, $\{[0, 10], [0, 9], \dots, [0, 0], [1, 10], [1, 9], \dots, [1, 1], [2, 10], [2, 9], \dots\}$
 - ▶ this guarantees that once we consider Δ , no $\Delta' \supseteq \Delta$ will be considered at later stage
- compute the **lower bound lb on the order** of a span-core in Δ to be recognized as maximal
- build the sets of vertices V_{lb} that have degree in Δ larger than lb
- extract the **innermost** core of the subgraph $(V_{lb}, E_{\Delta}[V_{lb}])$
- identify such a core as maximal if its order is actually larger than lb

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-
- the time complexity is still $\mathcal{O}(|T|^2 \times |E|)$

Experiments

Datasets

dataset	$ V $	$ E $	$ T $	window size (days)	domain
ProsperLoans	89k	3M	307	7	economic
Last.fm	992	4M	77	21	co-listening
WikiTalk	2M	10M	192	28	communication
DBLP	1M	11M	80	366	co-authorship
StackOverflow	2M	16M	51	56	question-and-answer
Wikipedia	343k	18M	101	56	co-editing
Amazon	2M	22M	115	28	co-rating
Epinions	120k	33M	25	21	co-rating

Evaluation

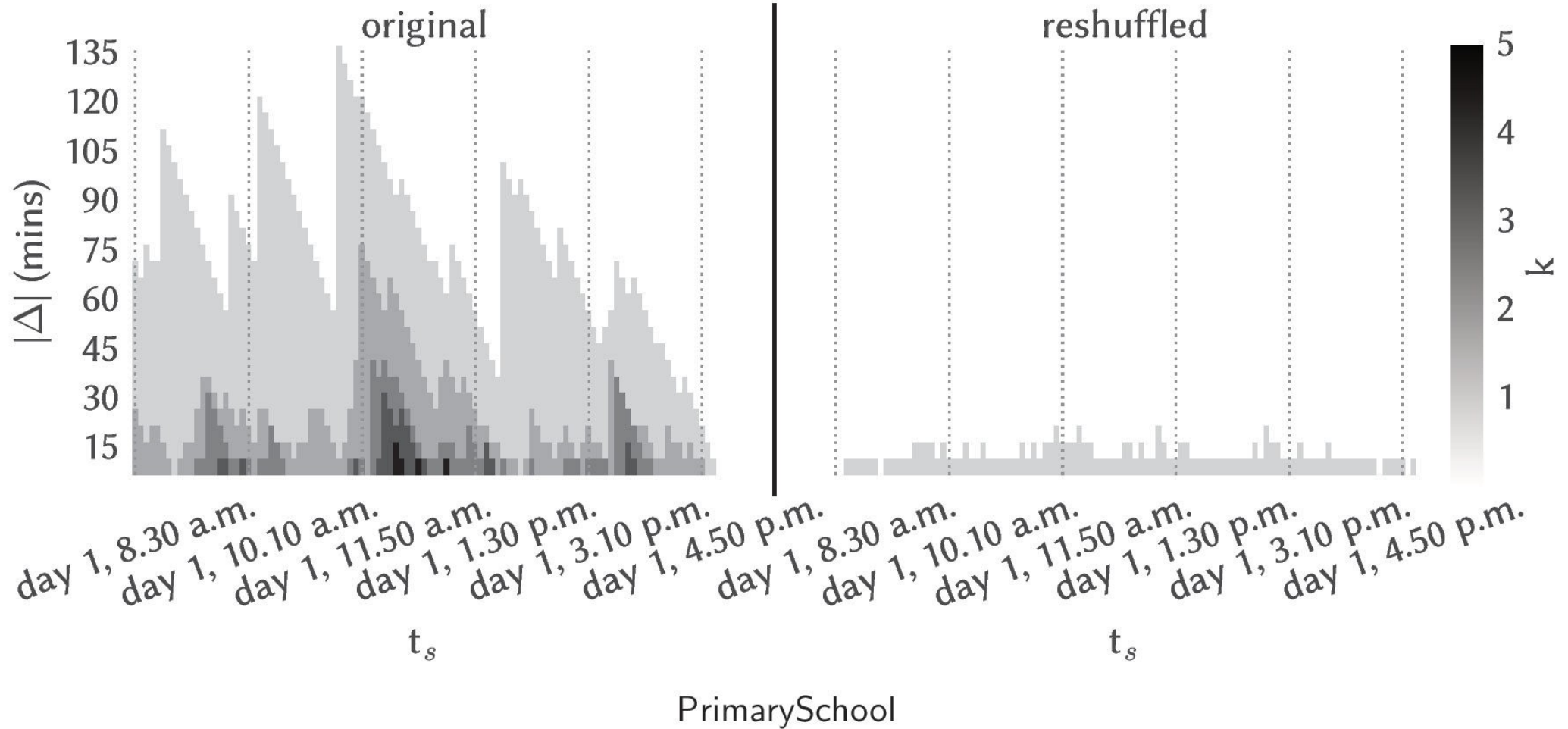
dataset	method	# output span-cores	time (s)	memory (GB)	# processed vertices
WikiTalk	Naïve-span-cores	19 693	322 302	36	25B
	Span-cores		1 084	36	555M
	Naïve-maximal-span-cores	632	1 194	36	555M
	Maximal-span-cores		126	35	2M
Wikipedia	Naïve-span-cores	125 191	17 155	4	1B
	Span-cores		522	4	35M
	Naïve-maximal-span-cores	2 147	537	4	35M
	Maximal-span-cores		201	4	320k
Amazon	Naïve-span-cores	29 318	10 415	18	2B
	Span-cores		409	18	247M
	Naïve-maximal-span-cores	303	580	18	247M
	Maximal-span-cores		123	18	688k

Applications

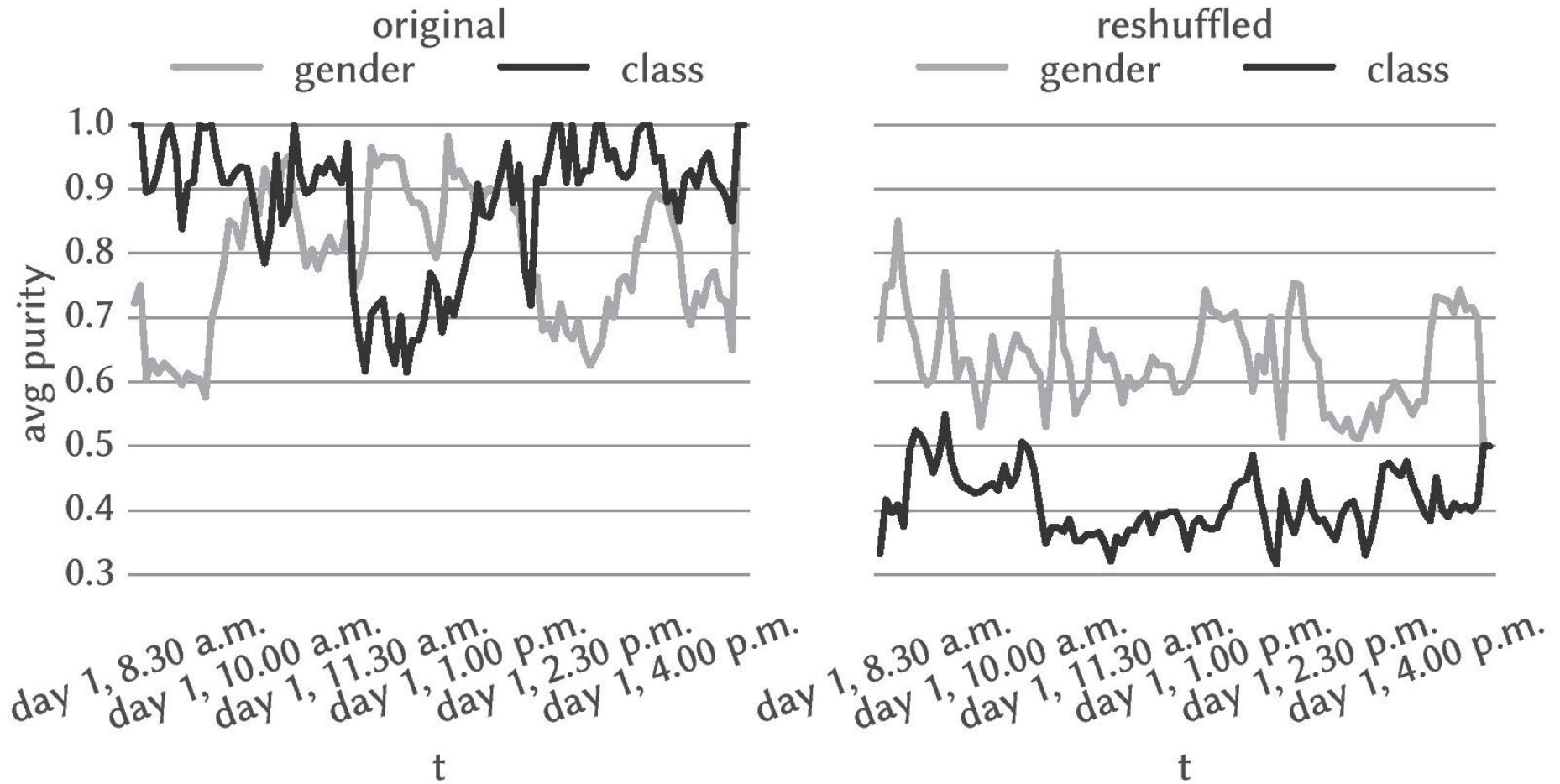
Datasets

- **face-to-face interaction networks** gathered by a proximity-sensing infrastructure in schools
 - ▶ PrimarySchool (242 individuals, 2 days)
 - ▶ HighSchool (327 individuals, 5 days)
 - ▶ HongKong (774 individuals, 11 days)
- window size of 5 minutes
- discarded span-cores of $|\Delta| = 1$

Social activities of groups of students

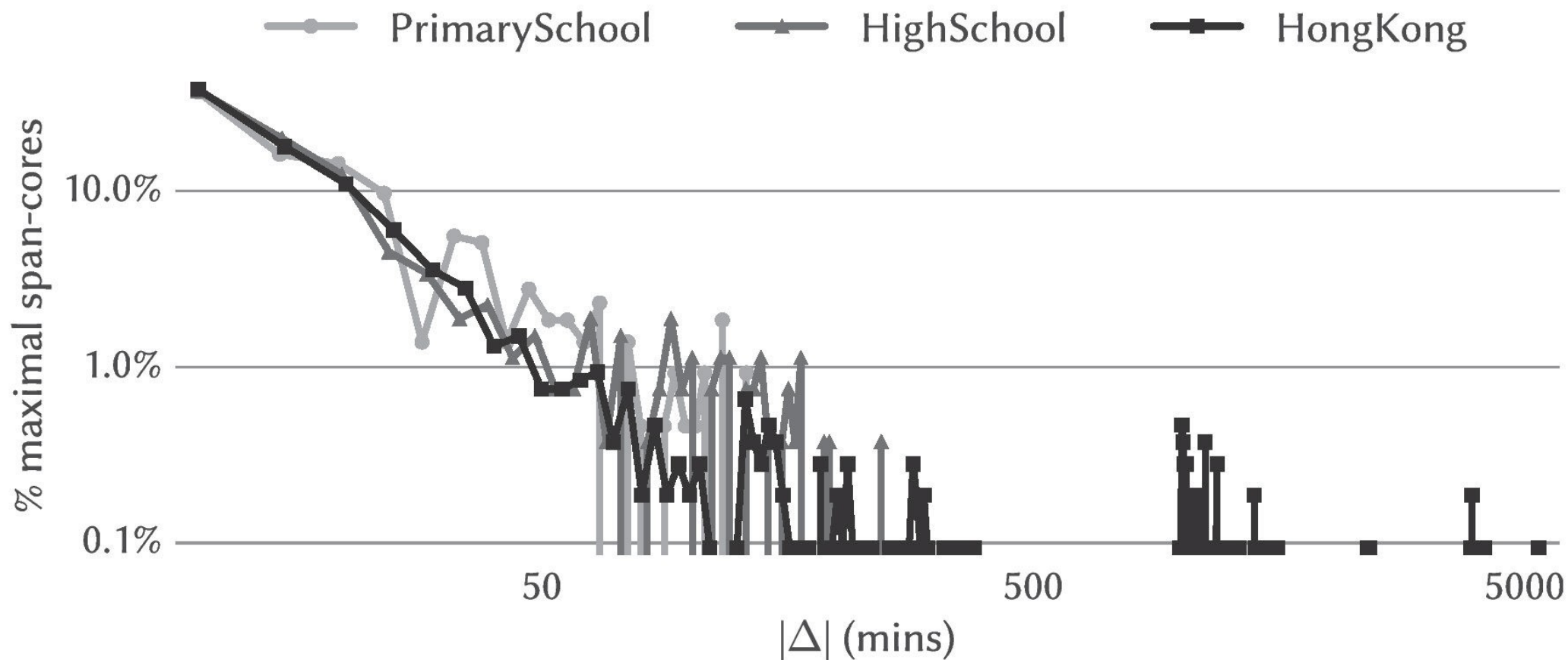


Mixing of gender and class

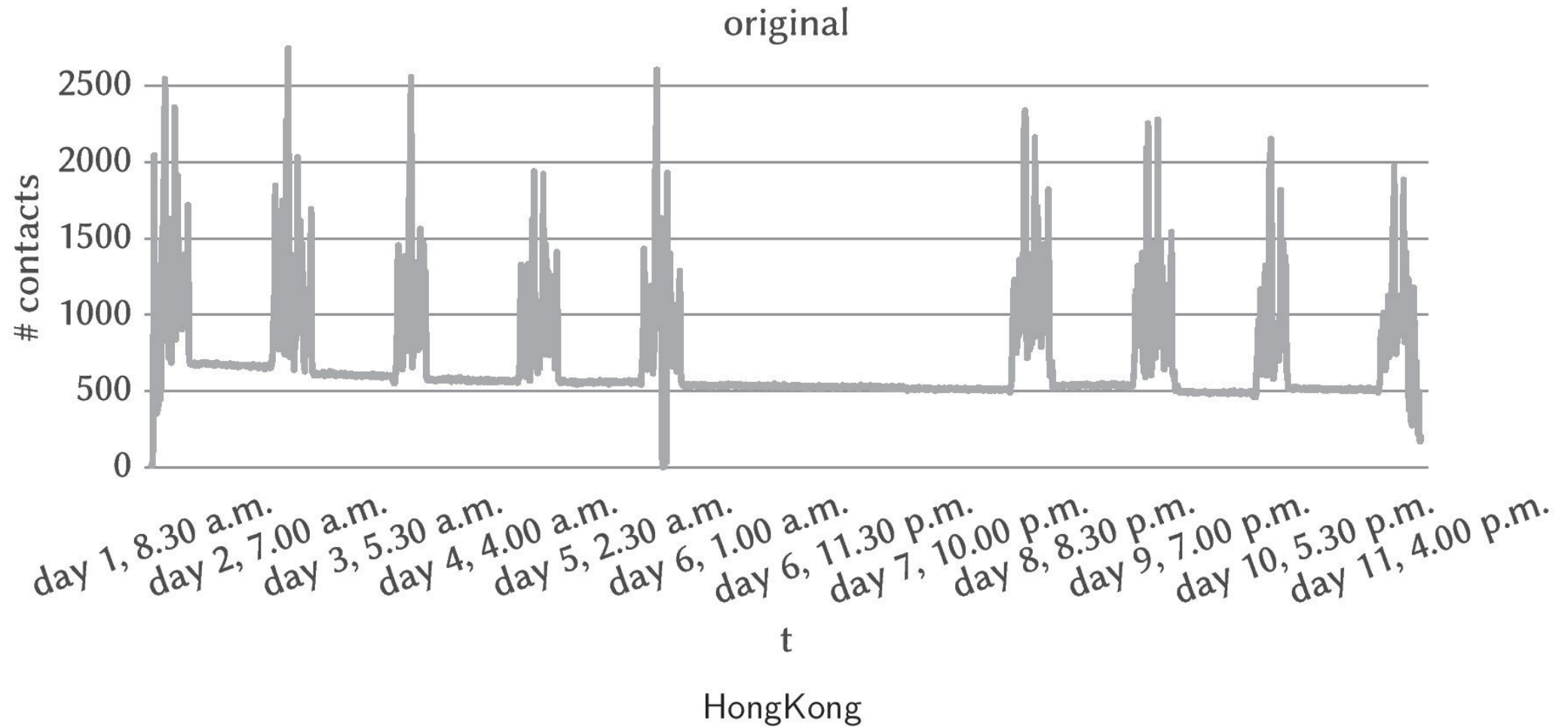


PrimarySchool

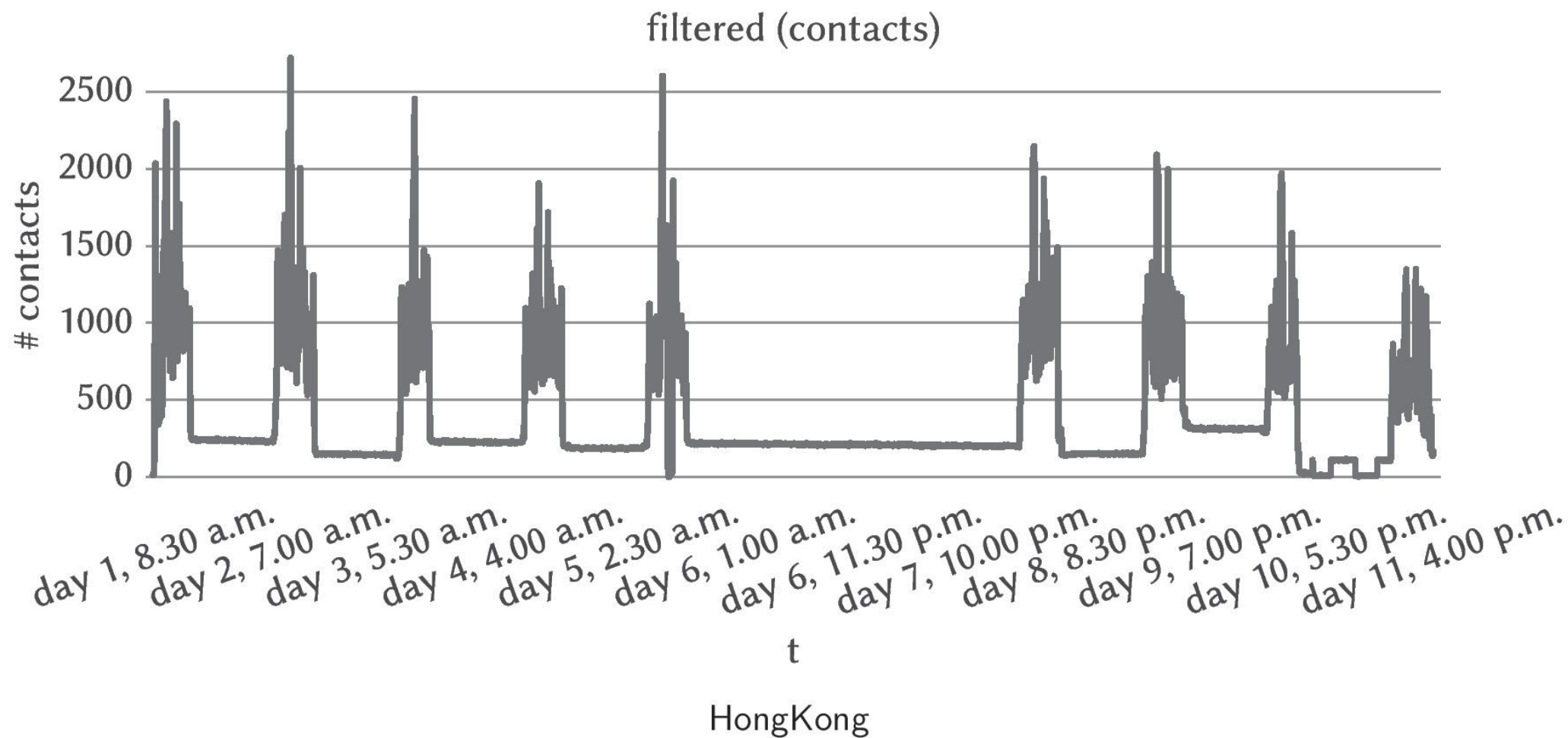
Length of social interactions in groups



Anomaly detection

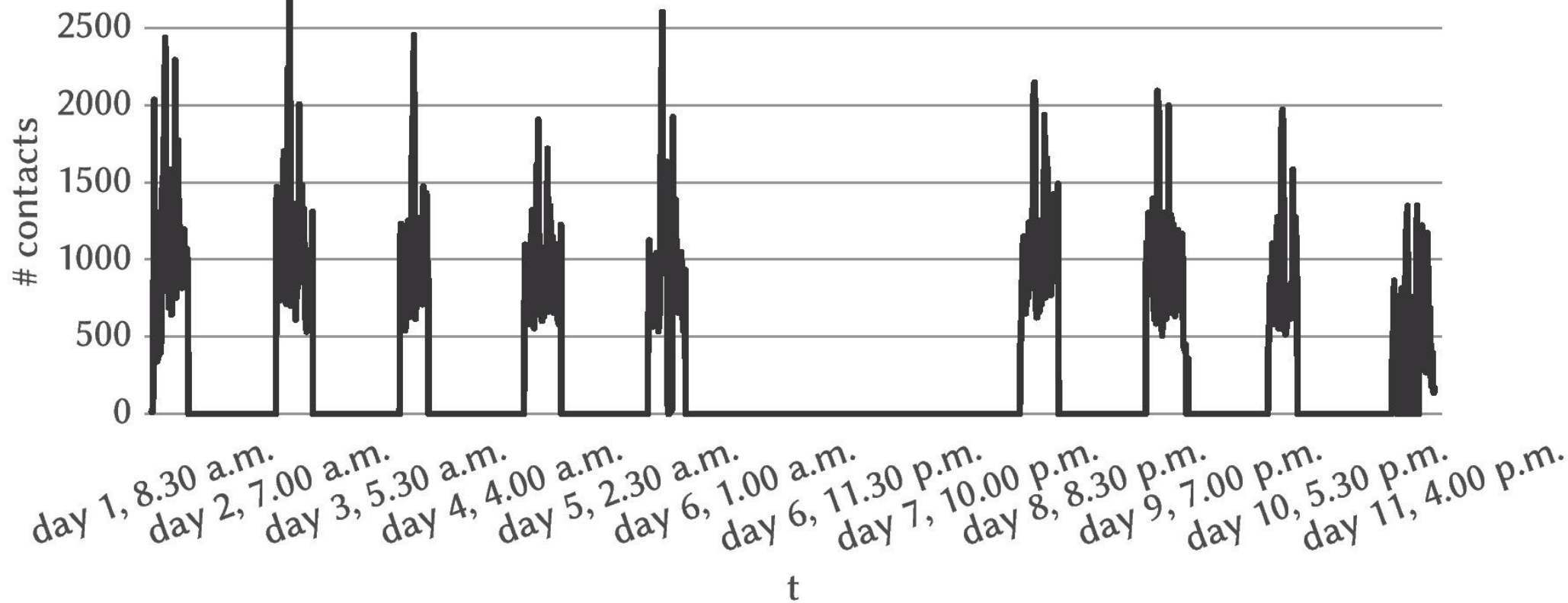


Anomaly detection



Anomaly detection

filtered (contacts and intervals)



HongKong

Conclusions

Conclusions

- introduced a notion of dense pattern in temporal networks that
 - ▶ takes into account the **sequentiality** of connections
 - ▶ is assigned with a clear **temporal collocation**
- developed efficient algorithms for computing all the span-cores, and only the maximal ones
- future work:
 - ▶ spreading processes analysis
 - ▶ temporal community search and temporal densest subgraph
 - ▶ network finger-printing

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