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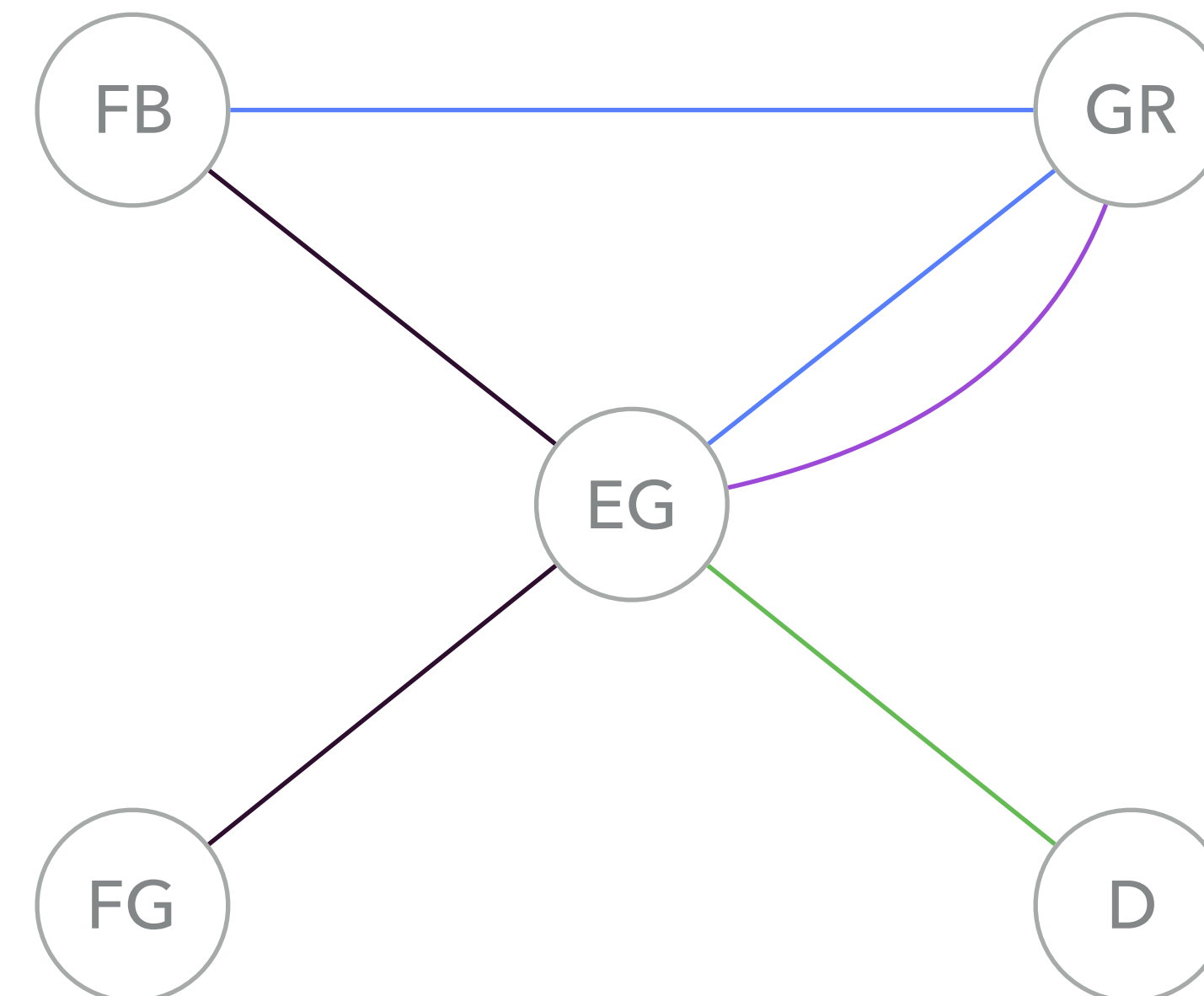
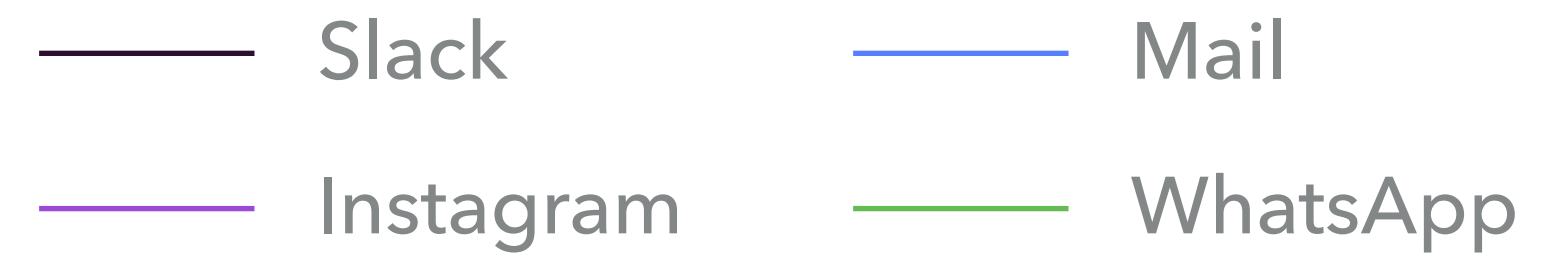
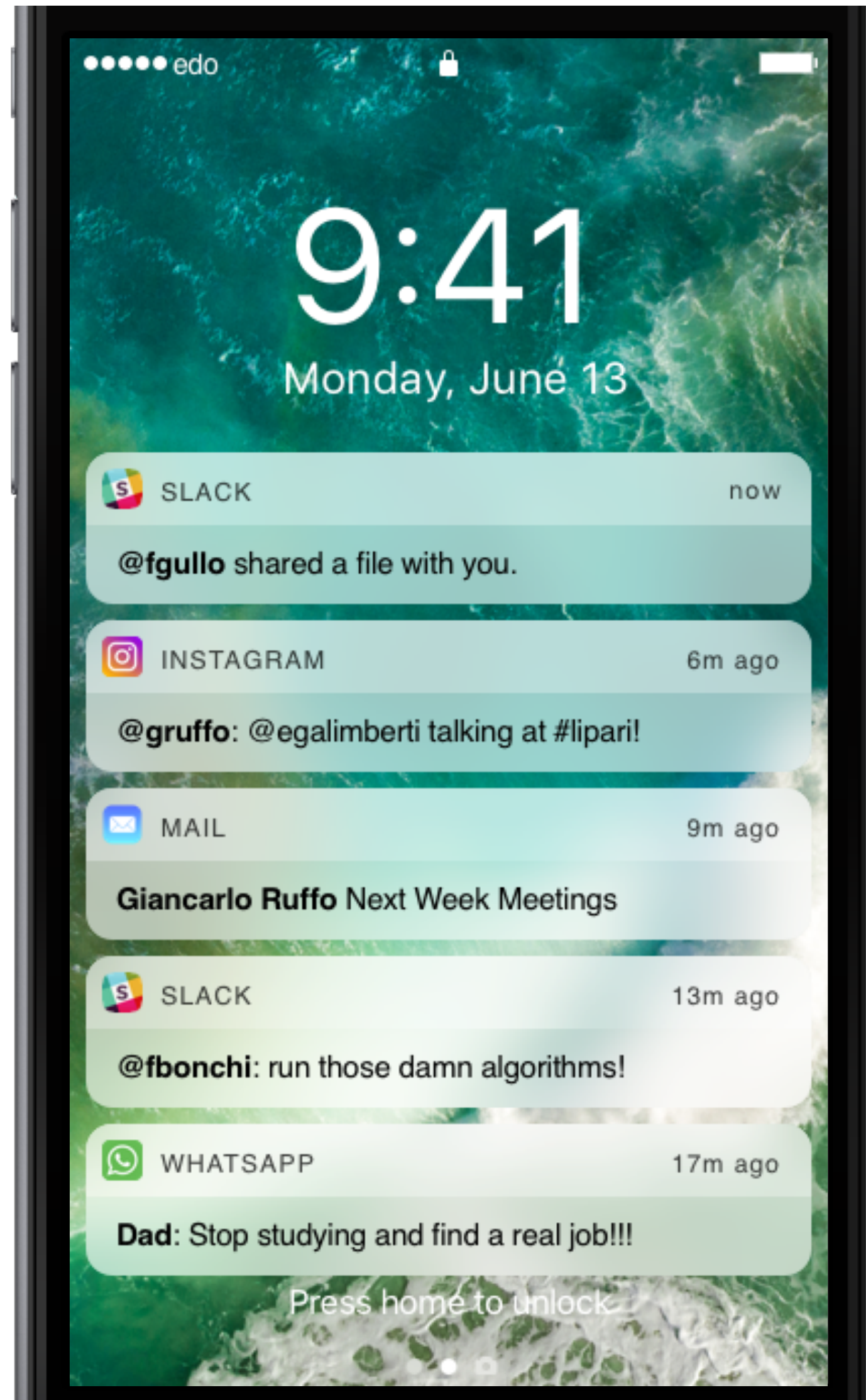
CORE DECOMPOSITION AND DENSEST SUBGRAPH IN MULTILAYER NETWORKS

AGENDA

- ▶ Multilayer Networks
- ▶ Core Decomposition and Densest Subgraph
- ▶ Multilayer Core Decomposition
- ▶ Experiments
- ▶ Multilayer Densest Subgraph

MULTILAYER NETWORKS

MULTILAYER NETWORKS



MULTILAYER NETWORKS

- ▶ Many real-world applications:
 - ▶ social media
 - ▶ biology
 - ▶ finance
 - ▶ transportation systems
 - ▶ critical infrastructures
- ▶ Represented by **multilayer graphs** $G=(V,E,L)$ where
 - ▶ V is a set of **vertices**
 - ▶ L is a set of **layers**
 - ▶ $E \subseteq V \times V \times L$ is a set of **labeled edges**

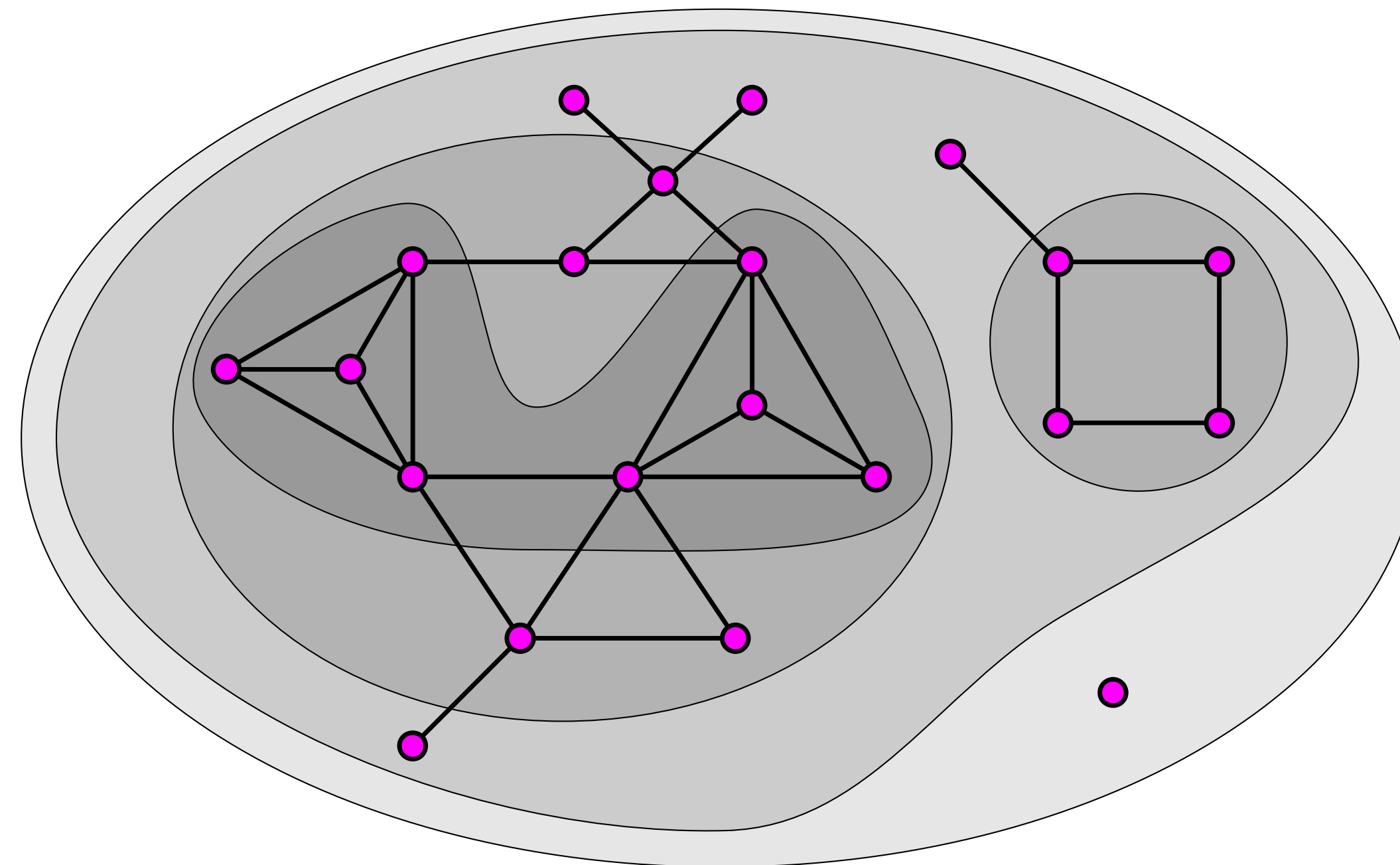
CORE DECOMPOSITION AND DENSEST SUBGRAPH

CORE DECOMPOSITION

Given a simple, single-layer, graph G .

The **k-core** (or core of order k) of G is a maximal subgraph $G[C_k]$ such that every vertex u in C_k has degree at least k .

The set of all k -cores forms the **core decomposition** of G .



CORE DECOMPOSITION

- ▶ It can be computed in linear time
- ▶ It has been studied for various types of graph
 - ▶ uncertain
 - ▶ directed
 - ▶ weighted
- ▶ Azimi-Tafreshi *et al.* study the **core-percolation problem** on multilayer networks from a physics standpoint, **without providing any algorithm**

DENSEST SUBGRAPH

Given a simple, single-layer, graph G .

The **densest subgraph** is the subgraph of G maximizing the average-degree density.

- ▶ Exact polynomial time algorithm
- ▶ Linear-time $1/2$ -approximation algorithm
- ▶ Jethava *et al.* formulate the **densest common subgraph** problem, i.e., find a subgraph maximizing the minimum average degree over **all layers**

MULTILAYER CORE DECOMPOSITION

MULTILAYER CORE DECOMPOSITION

Let $G=(V,E,L)$ be a multilayer graph and an $|L|$ -dimensional integer vector $\mathbf{k}=[k_l]$.

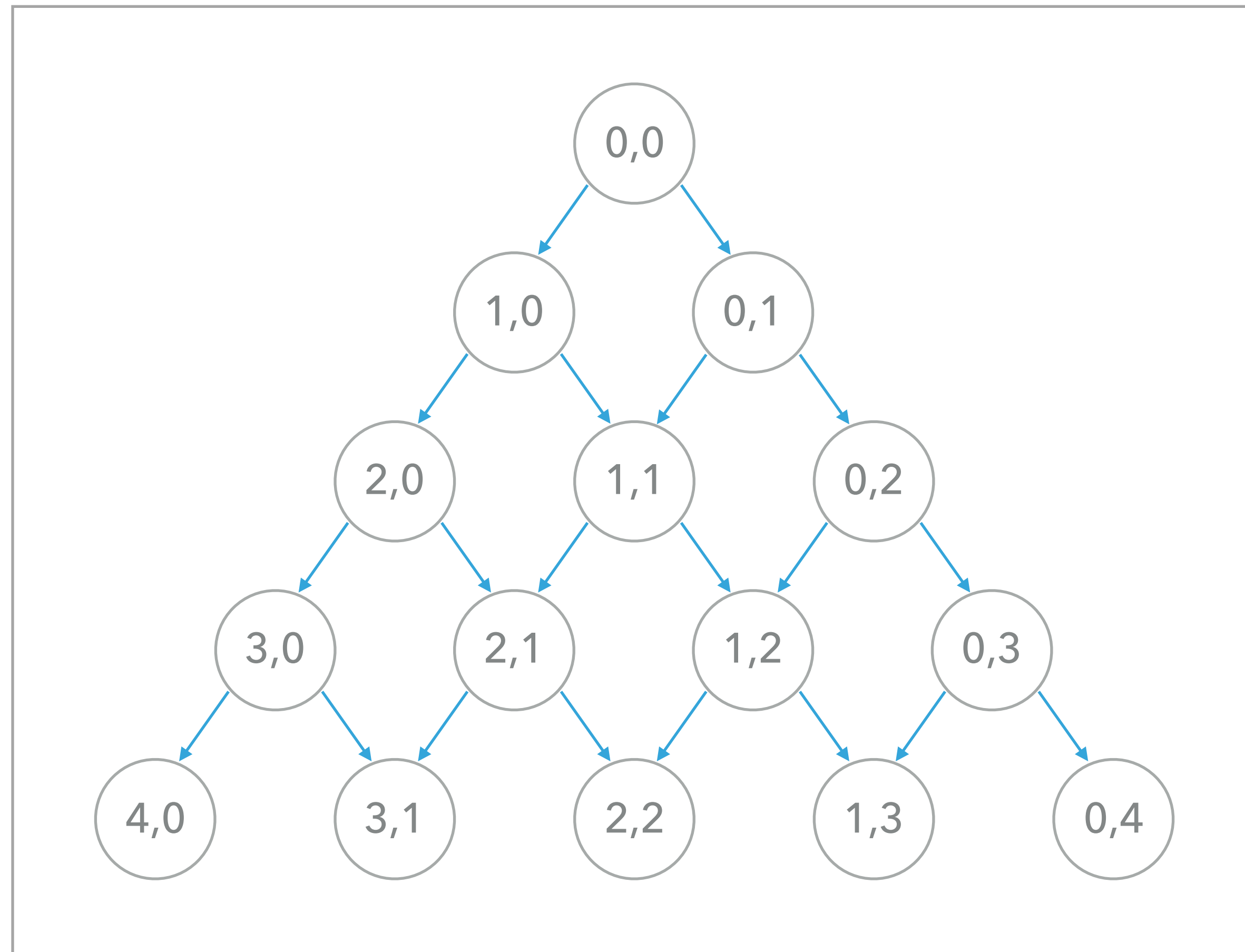
The **multilayer \mathbf{k} -core** of G is a maximal subgraph $G[C_{\mathbf{k}}]$ whose vertices have at least degree k_l in $C_{\mathbf{k}}$, for all layers l in L .

Given a multilayer graph $G=(V,E,L)$, find the set of all **non-empty** and **distinct** multilayer cores of G .

Such a set constitutes the **multilayer core decomposition** of G .

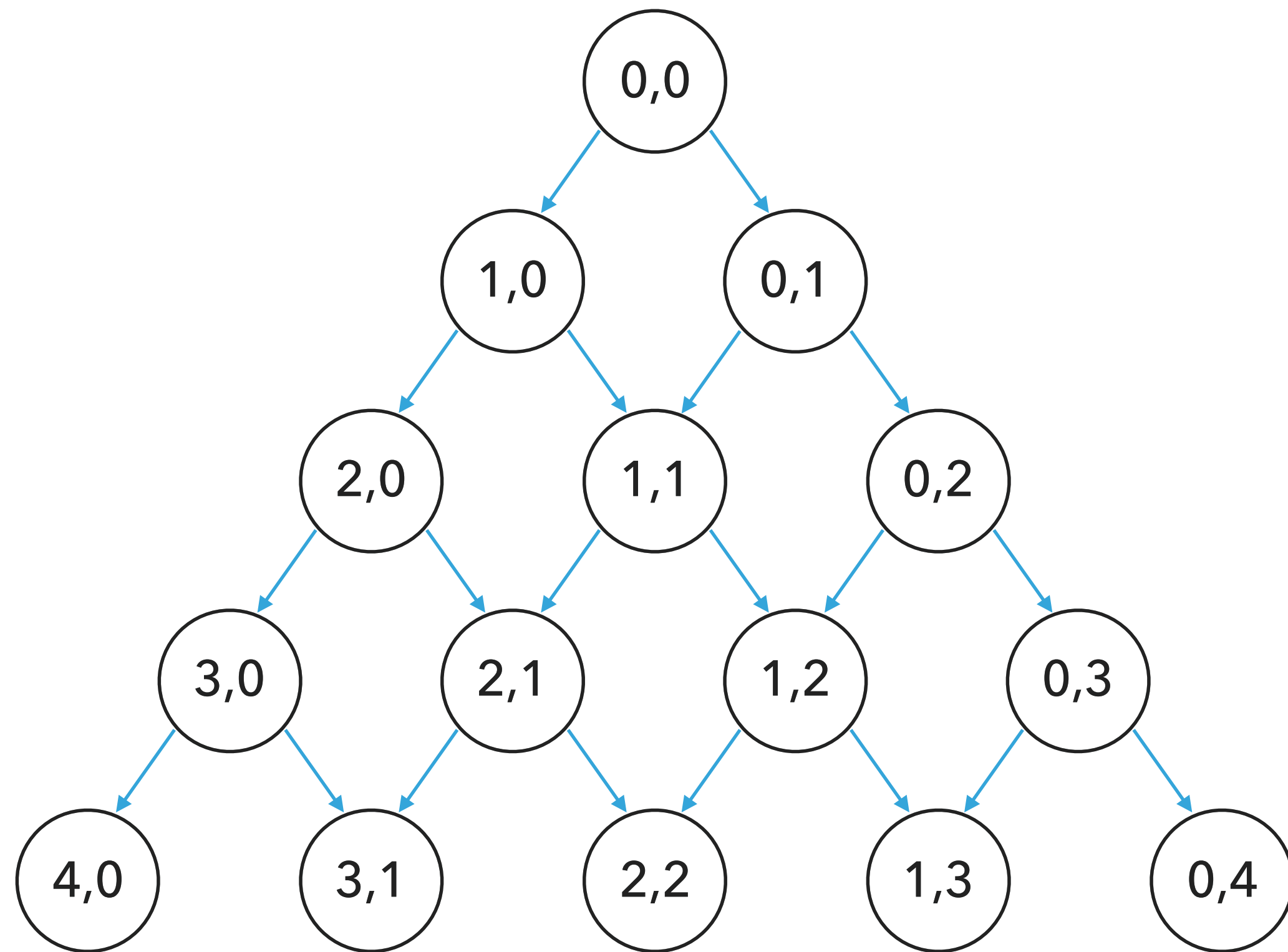
- ▶ The number of multilayer cores to be output may be exponential in the number of layers
- ▶ **No polynomial-time algorithm can exist**

SEARCH SPACE: CORE LATTICE



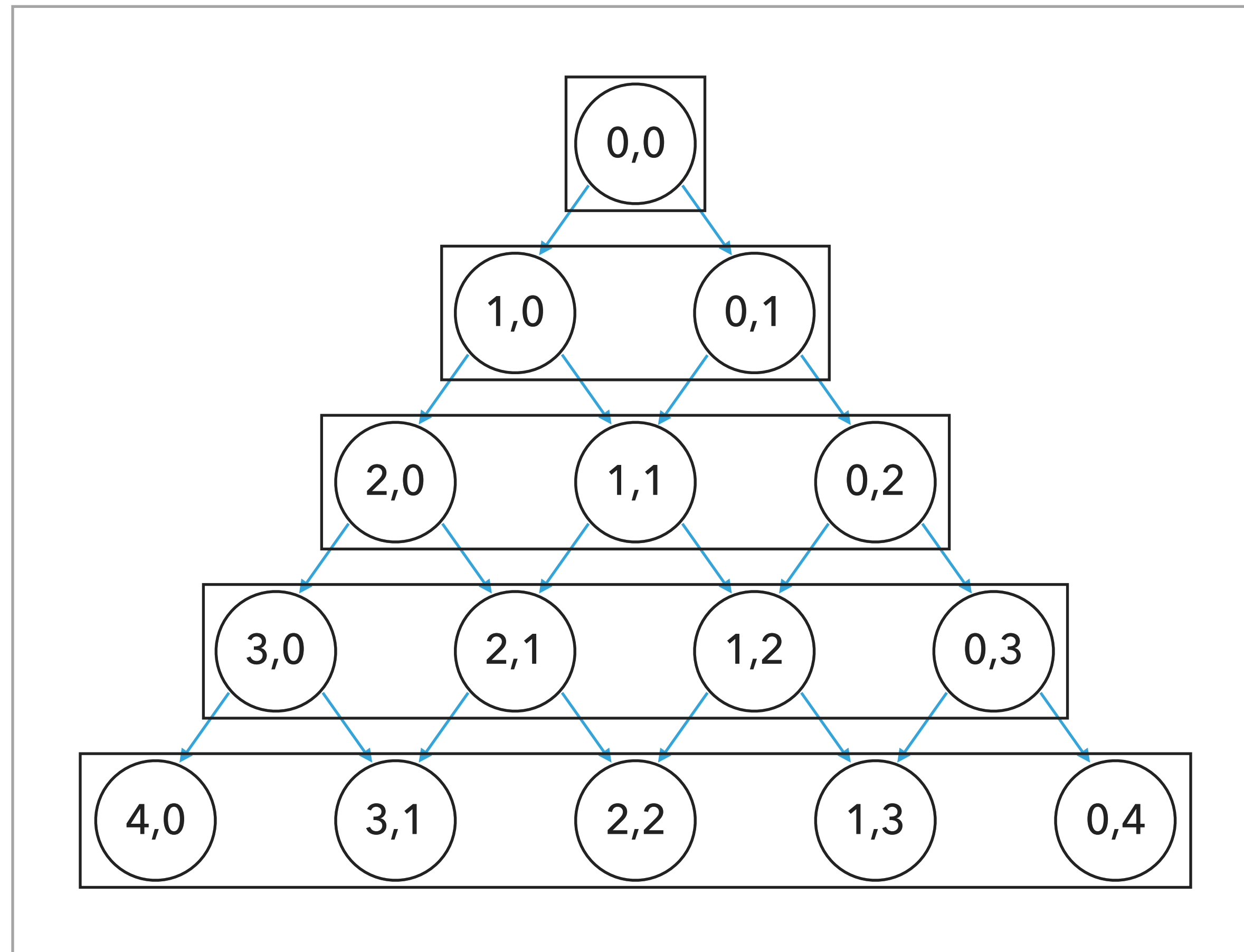
- ▶ A \mathbf{k} -core with coreness vector $\mathbf{k}=[k_i]$ is **contained** into any \mathbf{k}' -core described by a coreness vector $\mathbf{k}'=[k'_i]$ whose components k'_i are all no more than components k_i

NAIVE ALGORITHM



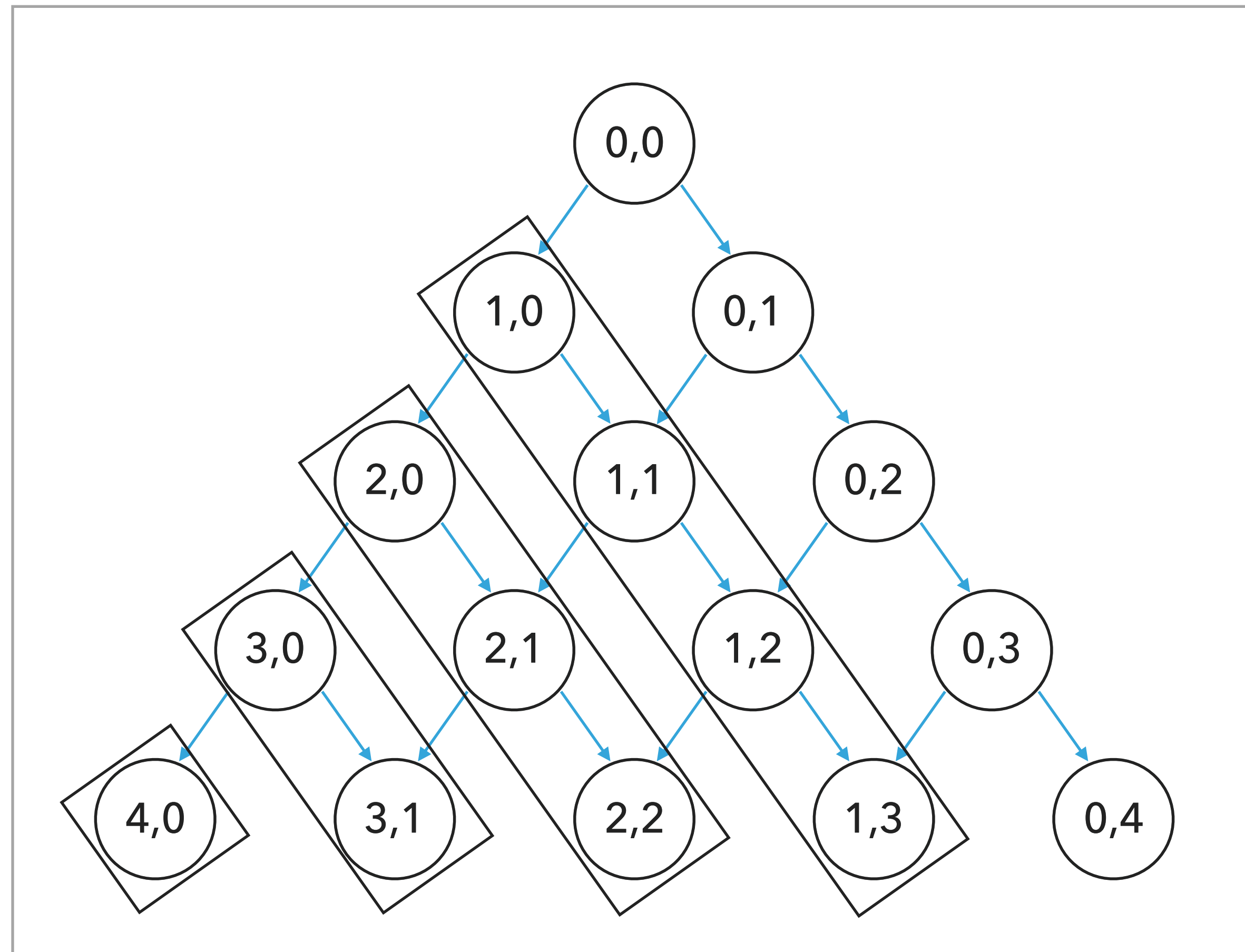
- ▶ Every possible core is computed separately and without a specific ordering
- ▶ Weaknesses:
 - ▶ each core is computed starting from the whole input graph
 - ▶ a lot of non-distinct and/or empty (thus, unnecessary) cores may be computed

BREADTH-FIRST ALGORITHM



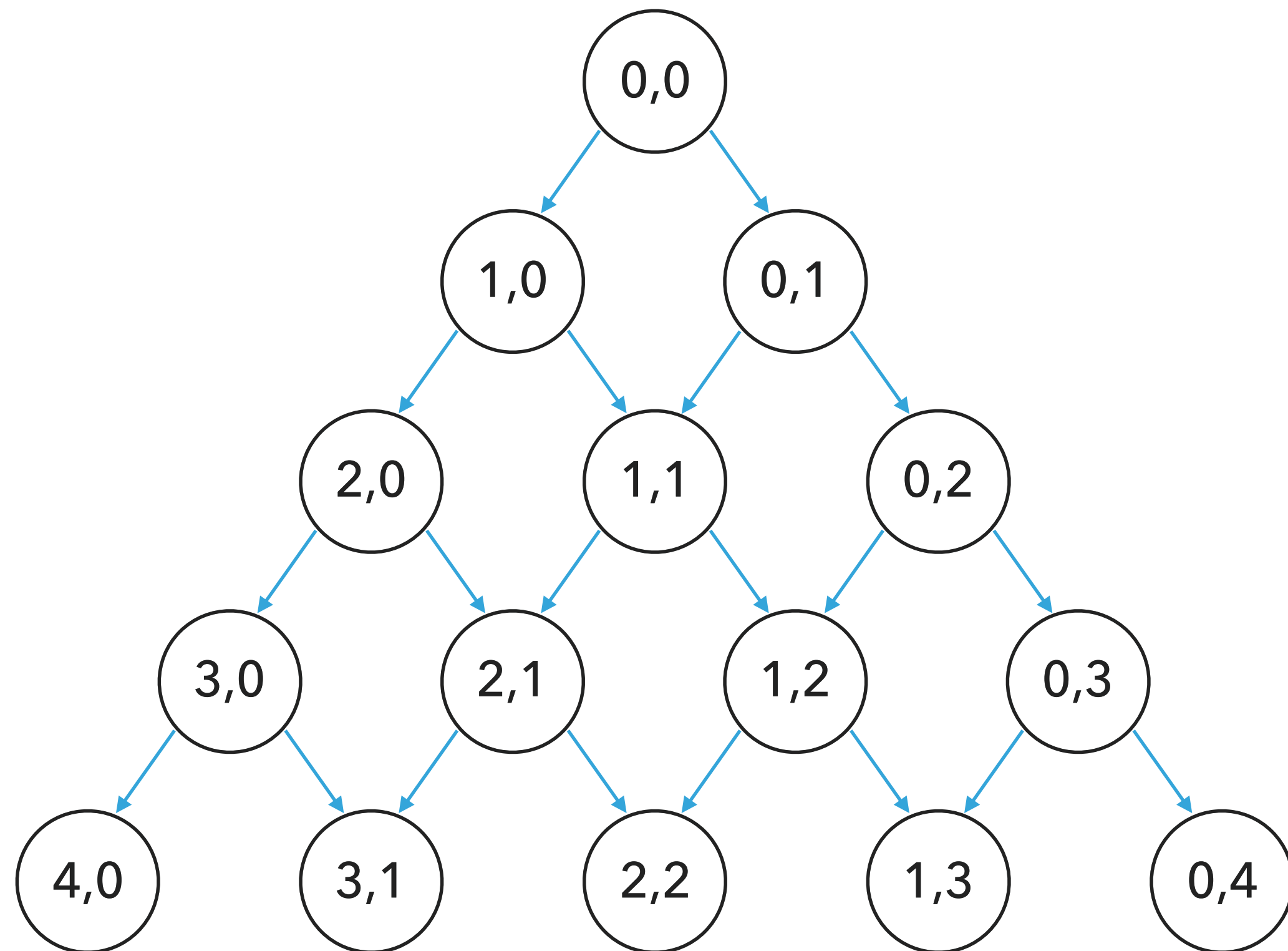
- ▶ The core lattice is explored **level by level**
- ▶ Cores are computed from the intersection of all their fathers
- ▶ Cores having less fathers than the number of non-zero components of its coreness vector \mathbf{k} are not visited
- ▶ Weaknesses:
 - ▶ the computation of the cores within a straight path can be performed more efficiently
 - ▶ non-distinct cores are computed

DEPTH-FIRST ALGORITHM



- ▶ The core lattice is explored **path by path**, resembling a depth-first search
- ▶ The algorithm iteratively picks a non-leaf core $\mathbf{k}=[k_i]$ and computes all cores in the path varying a component of k
- ▶ Not all paths have to be explored to visit the whole core lattice
- ▶ Weaknesses:
 - ▶ cores may be computed multiple times
 - ▶ cores are computed starting from larger subgraphs
 - ▶ non-distinct cores are still computed

HYBRID ALGORITHM



- ▶ The algorithm starts with a single-layer core decomposition for each layer
- ▶ Then it performs a breadth-first search equipped with a **“look-ahead” mechanism**
- ▶ All cores are computed once and non-distinct cores are skipped

EXPERIMENTS

CORE DECOMPOSITION AND DENSEST SUBGRAPH IN MULTILAYER NETWORKS

DATASETS

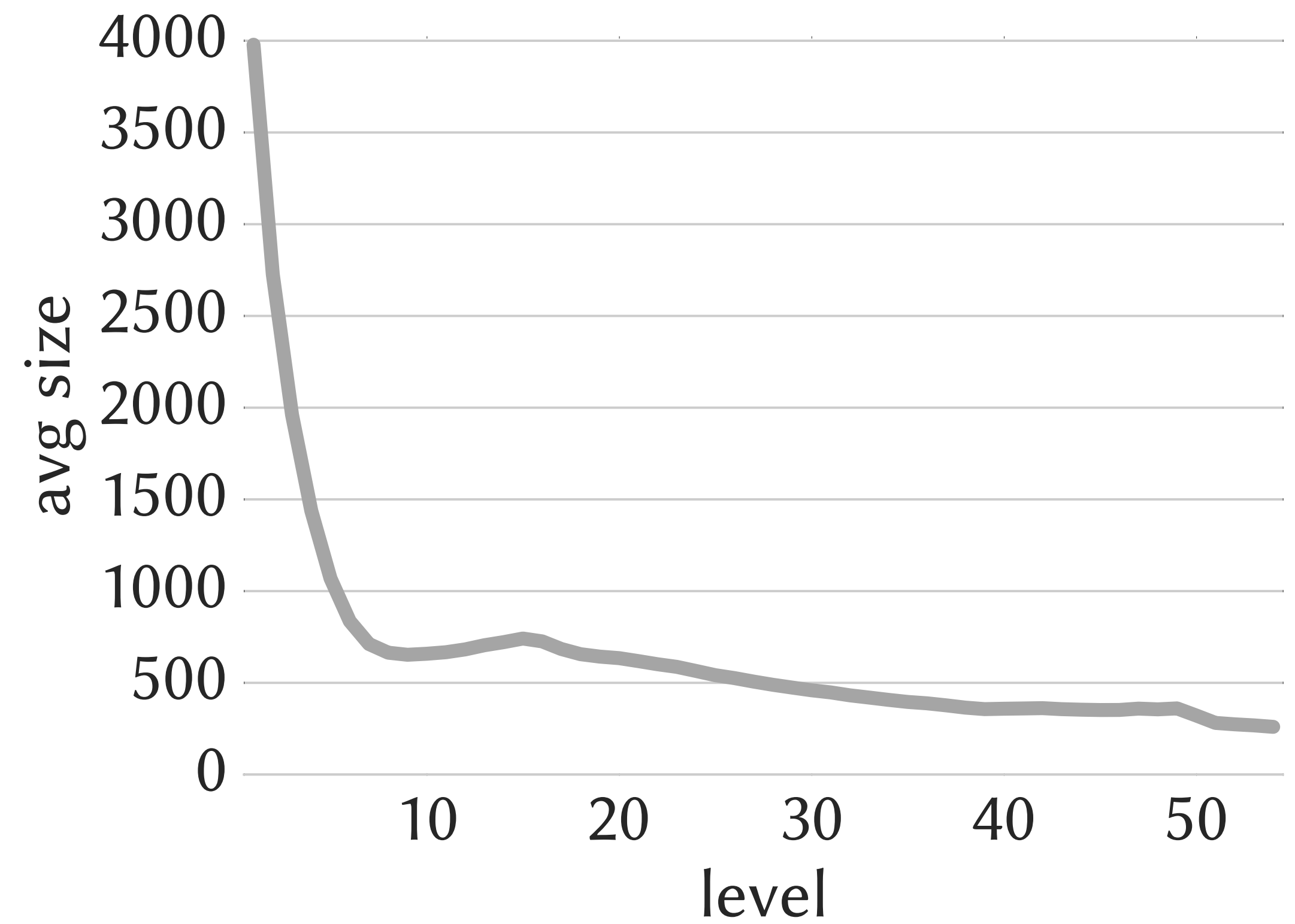
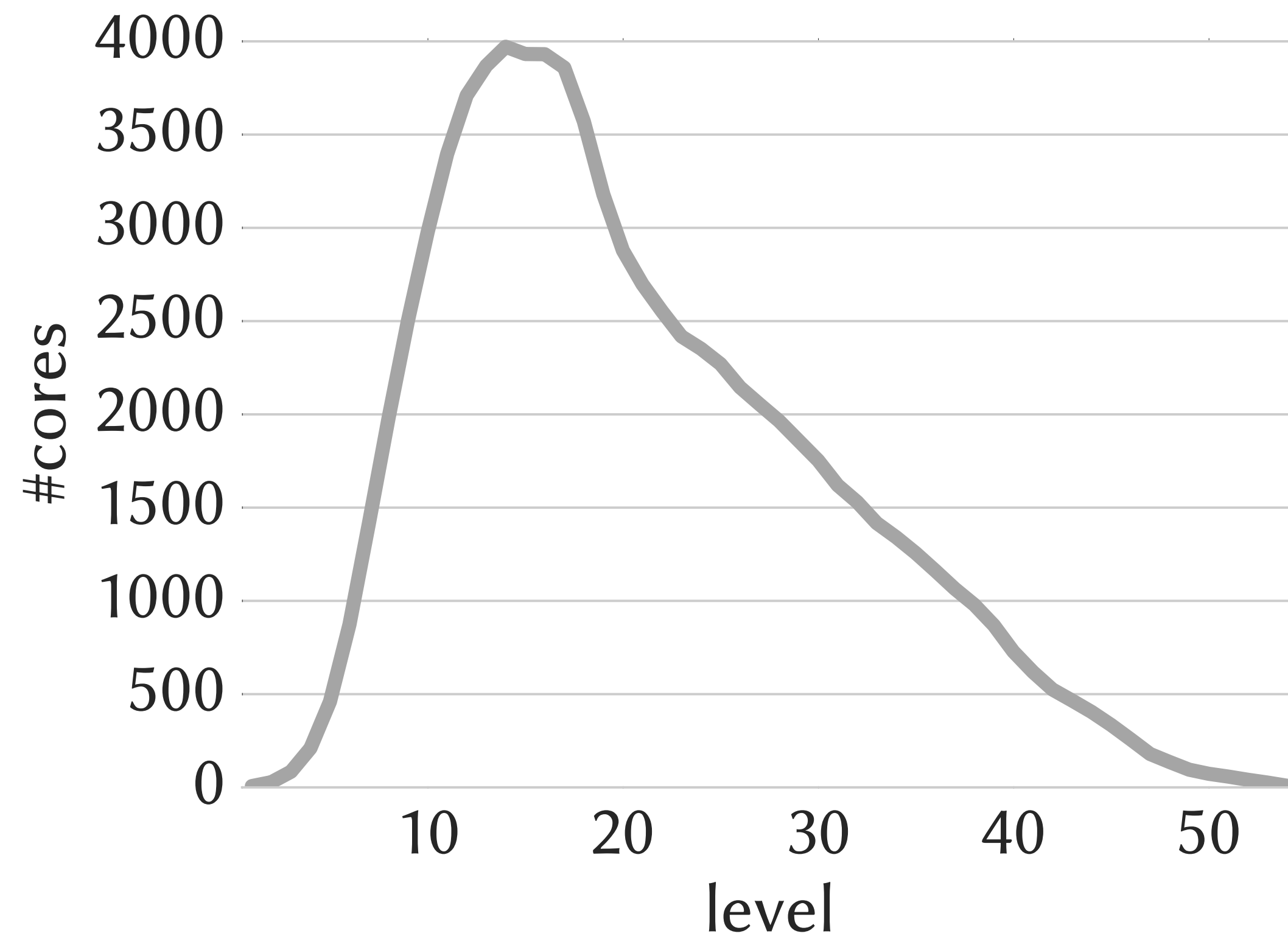
dataset	$ V $	$ E $	$ L $	domain
Homo	18k	153k	7	genetic
SacchCere	6.5k	247k	7	genetic
DBLP	513k	1.0	10	co-authorship
ObamaInIsrael	2.2M	3.8M	3	social
Amazon	410k	8.1M	4	co-purchasing
FriendfeedTwitter	155k	13M	2	social
Higgs	456k	13M	4	social
Friendfeed	510k	18M	3	social

CORE DECOMPOSITION AND DENSEST SUBGRAPH IN MULTILAYER NETWORKS

EFFICIENCY

dataset	#output cores	method	time (s)	#computed cores
SacchCere	74,426	N	19,282	278,402
		BFS	802	89,883
		DFS	2,117	223,643
		H	819	83,978
DBLP	3,346	N	104,361	34,572
		BFS	66	6,184
		DFS	219	38,887
		H	26	5,037
Amazon	1,164	BFS	2,349	1,354
		DFS	3,809	2,459
		H	2,464	1,334
Friendfeed	365,666	BFS	45,568	546,631
		DFS	12,211	568,107
		H	37,495	389,323

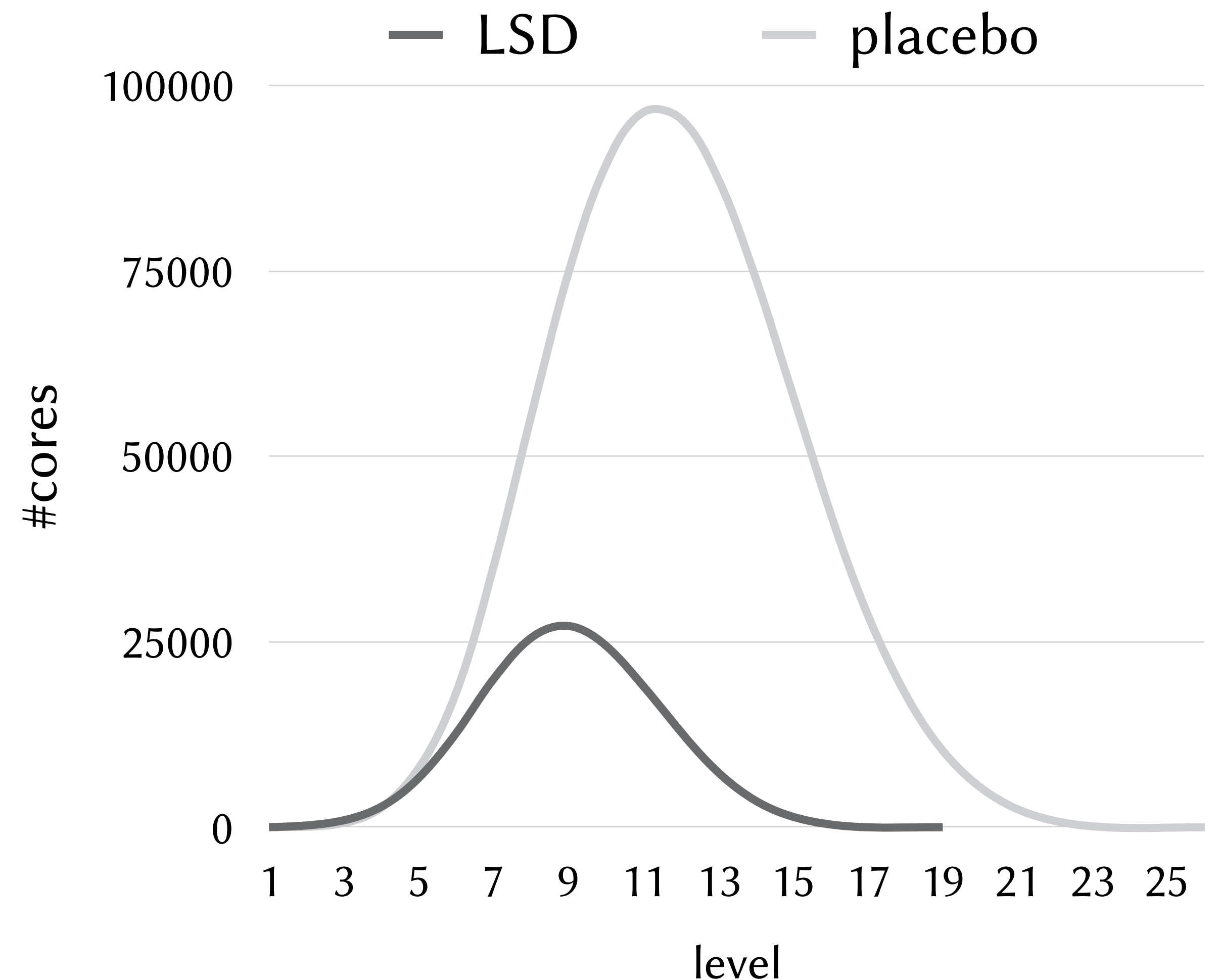
RESULTS



SacchCere

CASE STUDY: BRAIN

- ▶ Dataset to study the effect of LSD on the human brain:
 - ▶ 3 neuroimaging techniques
 - ▶ 15 individuals
 - ▶ 2 states
- ▶ 6 multilayer networks:
 - ▶ 165 vertices
 - ▶ 15 layers



**MULTILAYER DENSEST
SUBGRAPH**

MULTILAYER DENSEST SUBGRAPH

Given a multilayer graph $G=(V,E,L)$, a positive real number β , and a real-valued function

$$\delta(S) = \max_{\hat{L} \subseteq L} \min_{l \in \hat{L}} \frac{|E_l[S]|}{|S|} |\hat{L}|^\beta$$

find a subset S^* of V that maximizes function δ .

- ▶ β controls the importance of the two ingredients of the objective function δ
- ▶ Solving the problem allows for automatically finding a set of layers of interest for the densest subgraph S^*

APPROXIMATION ALGORITHM

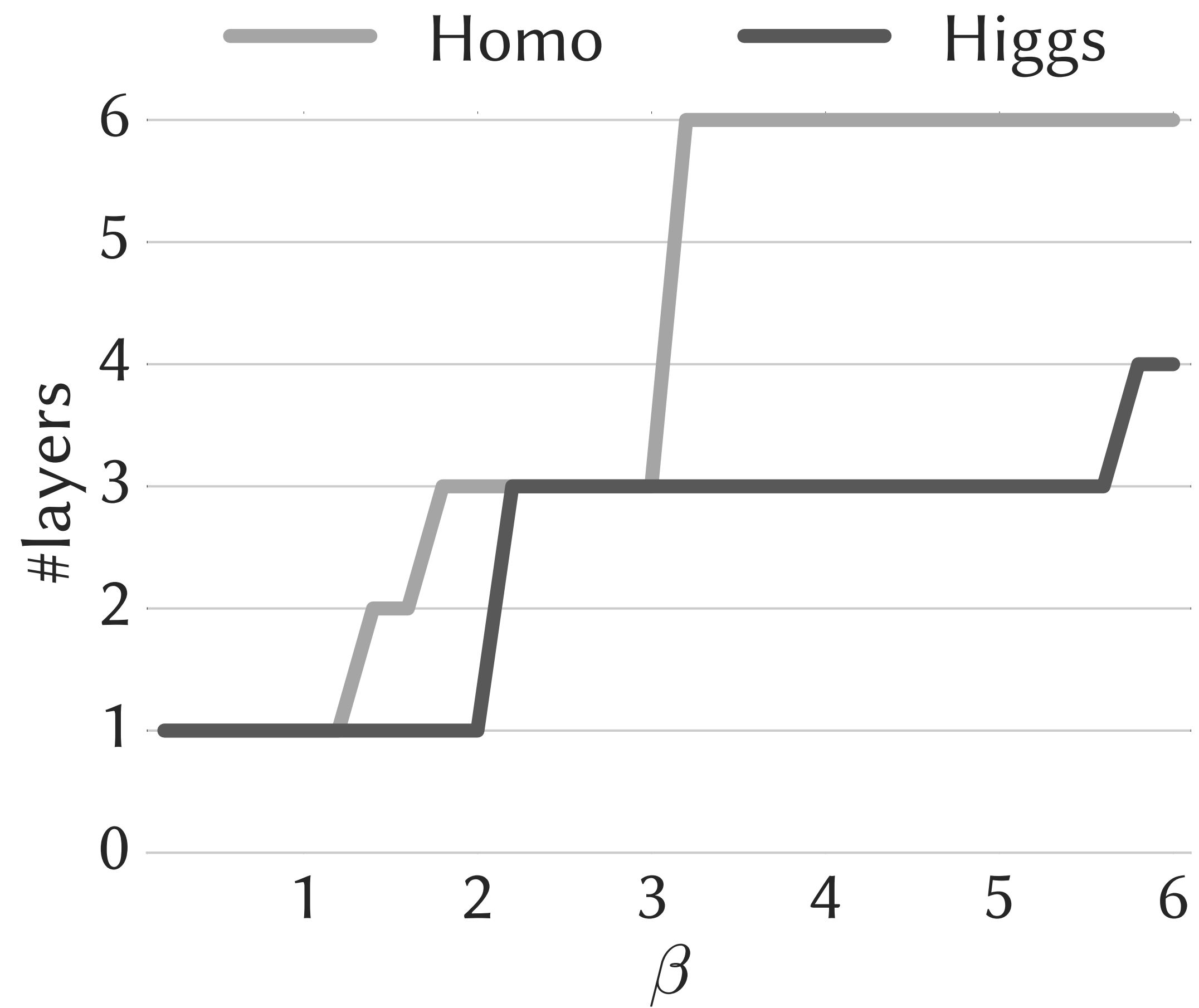
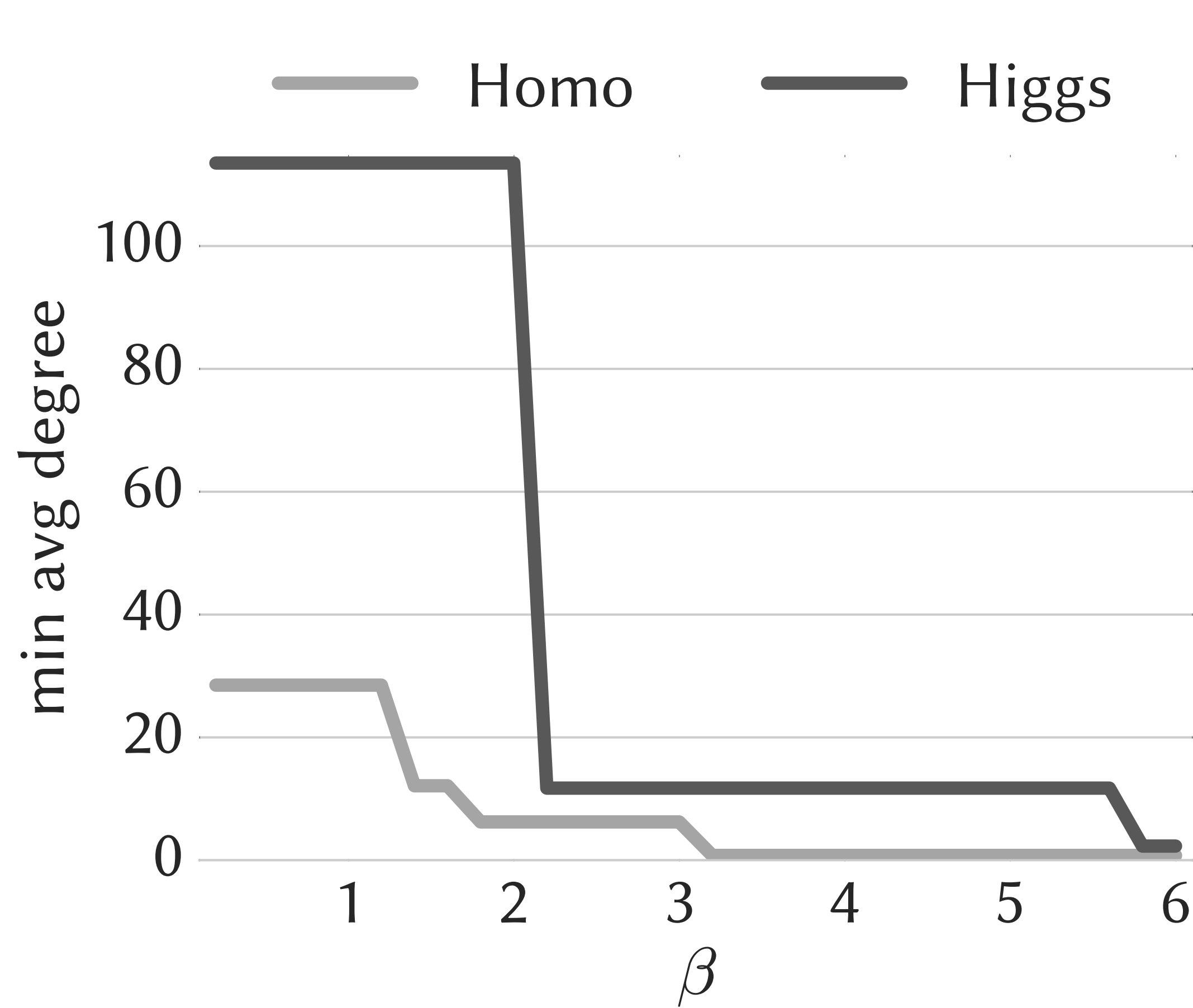
- ▶ Compute the multilayer core decomposition of the input graph
- ▶ Among all cores, take the one maximizing the objective function δ as the output densest subgraph

Let C^* denote the core maximizing the density function δ , then

$$\delta(C^*) \geq \frac{1}{2|L|^\beta} \delta(S^*),$$

i.e., the algorithm achieves **$1/2|L|^\beta$ approximation guarantees.**

RESULTS



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ANECDOTAL EVIDENCE: DBLP

